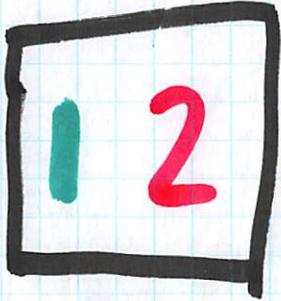
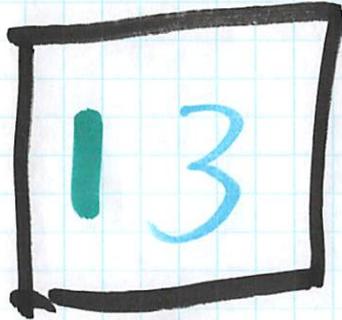


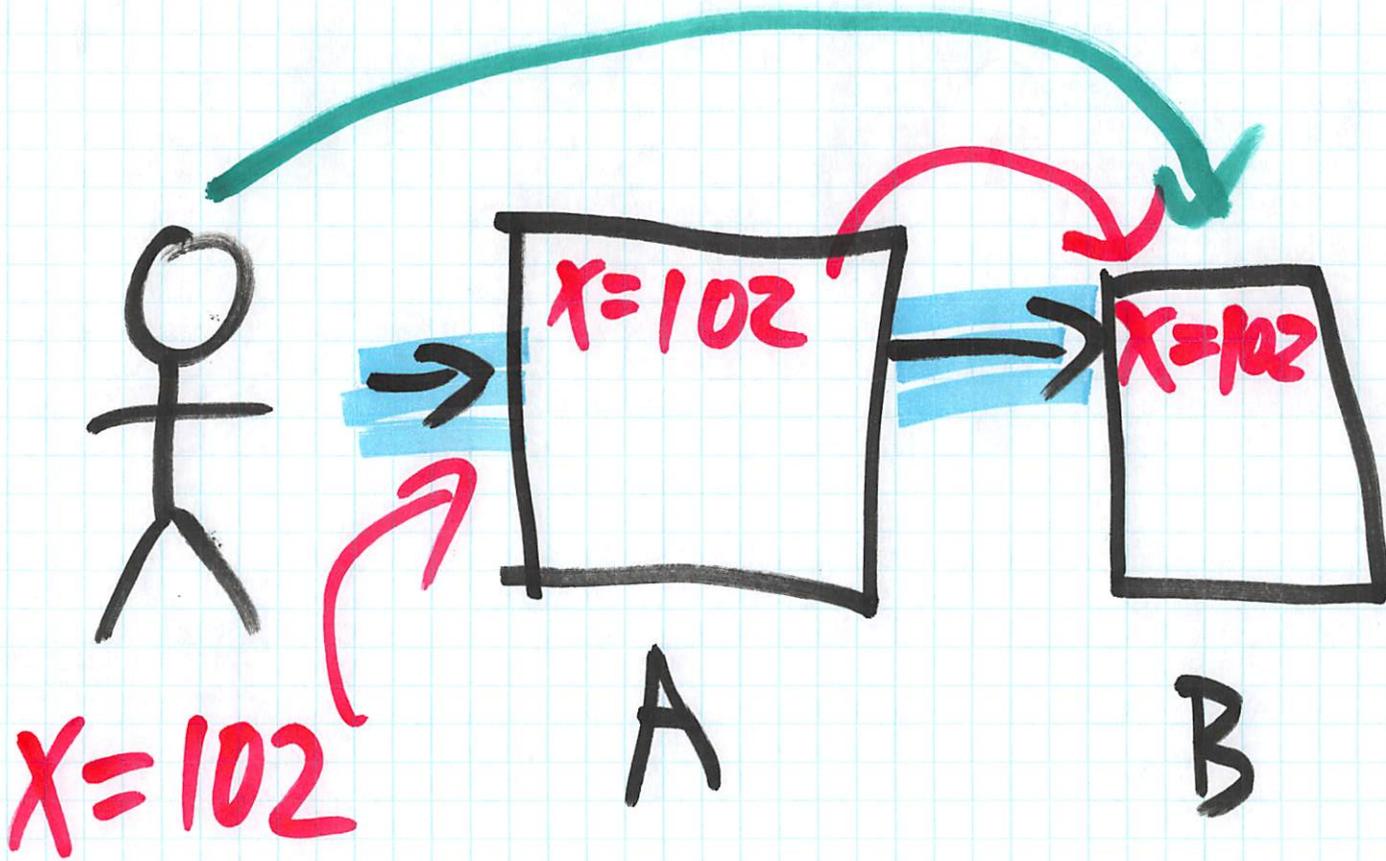
Parallel
Updates
(2 Queries Continued)



A



B



B fails

Nothing Happens

- B is restarted
- B catches up to A's state Yay!

A fails

Everything fails

Option 1 (Consistency) [- A is restarted

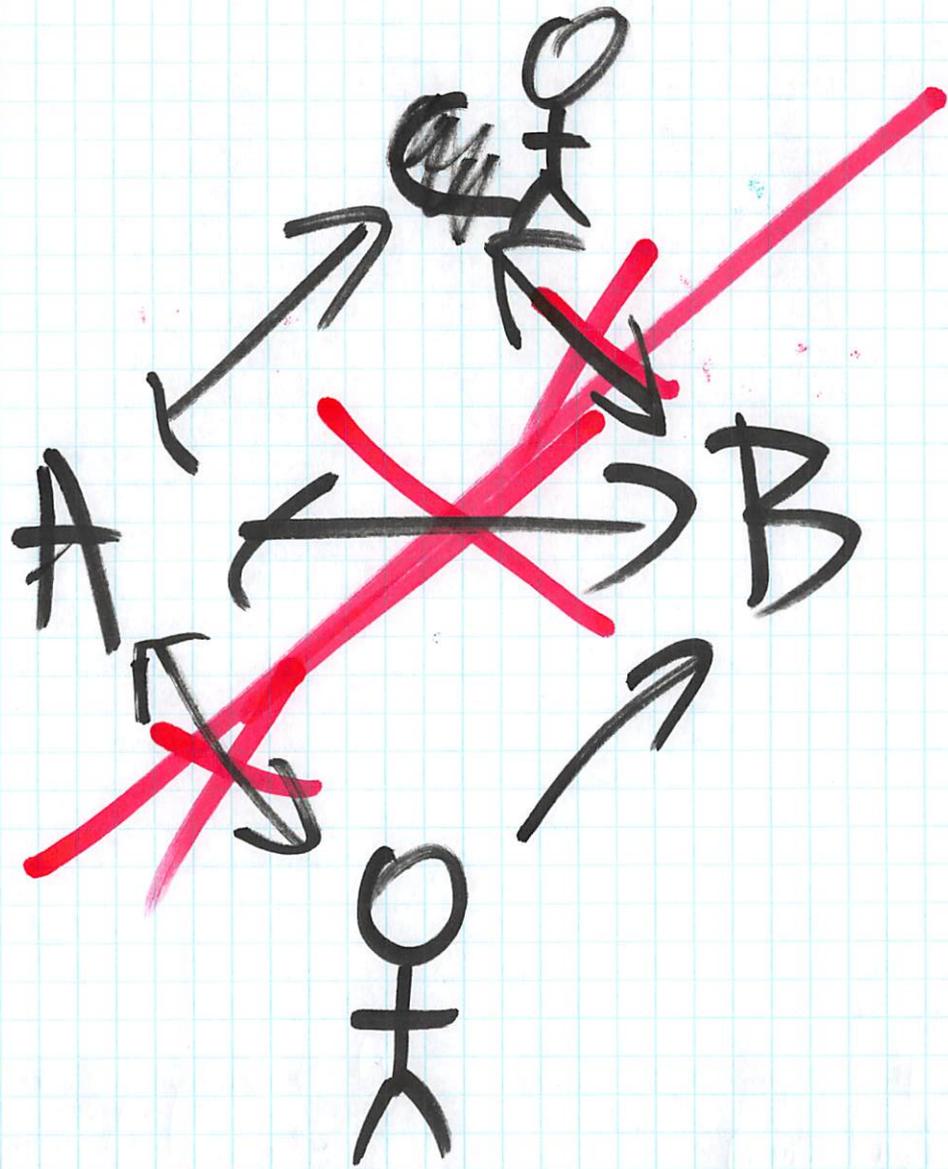
→ Option 2 (Availability) [- Switch over to B as Primary
- A reconnects as a follower

Why not option 2?

- B doesn't have an up to date view of the data

Network Fails

???



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or

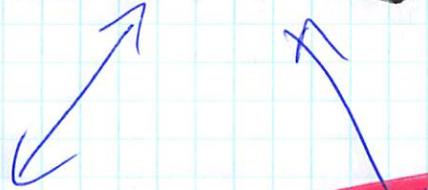
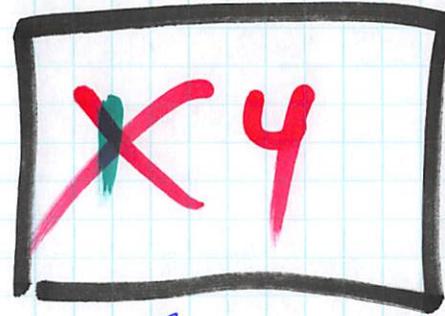
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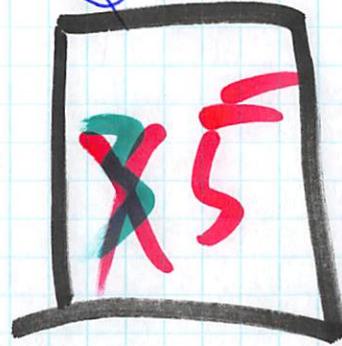
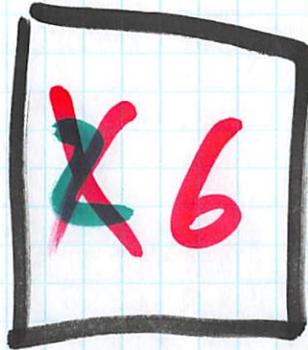
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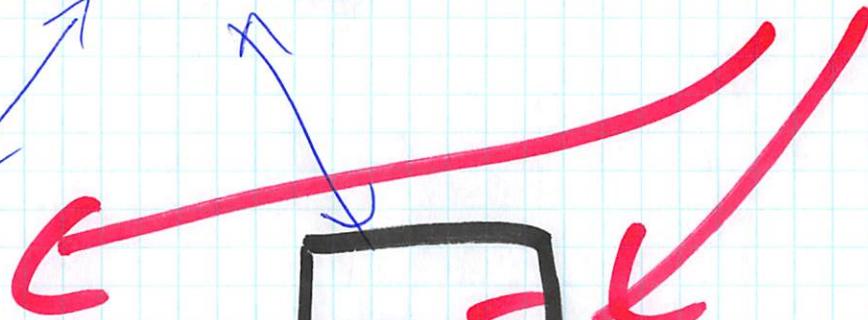
A

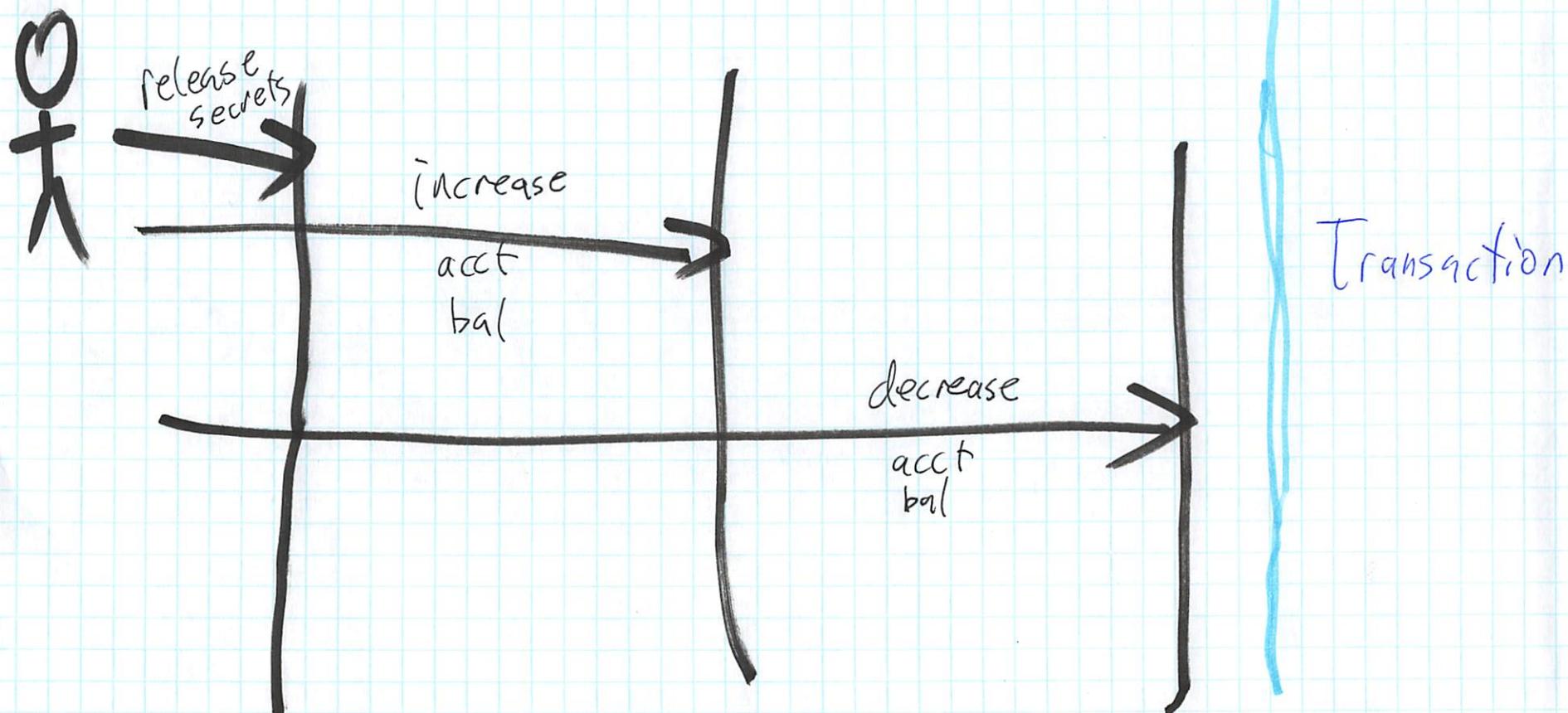


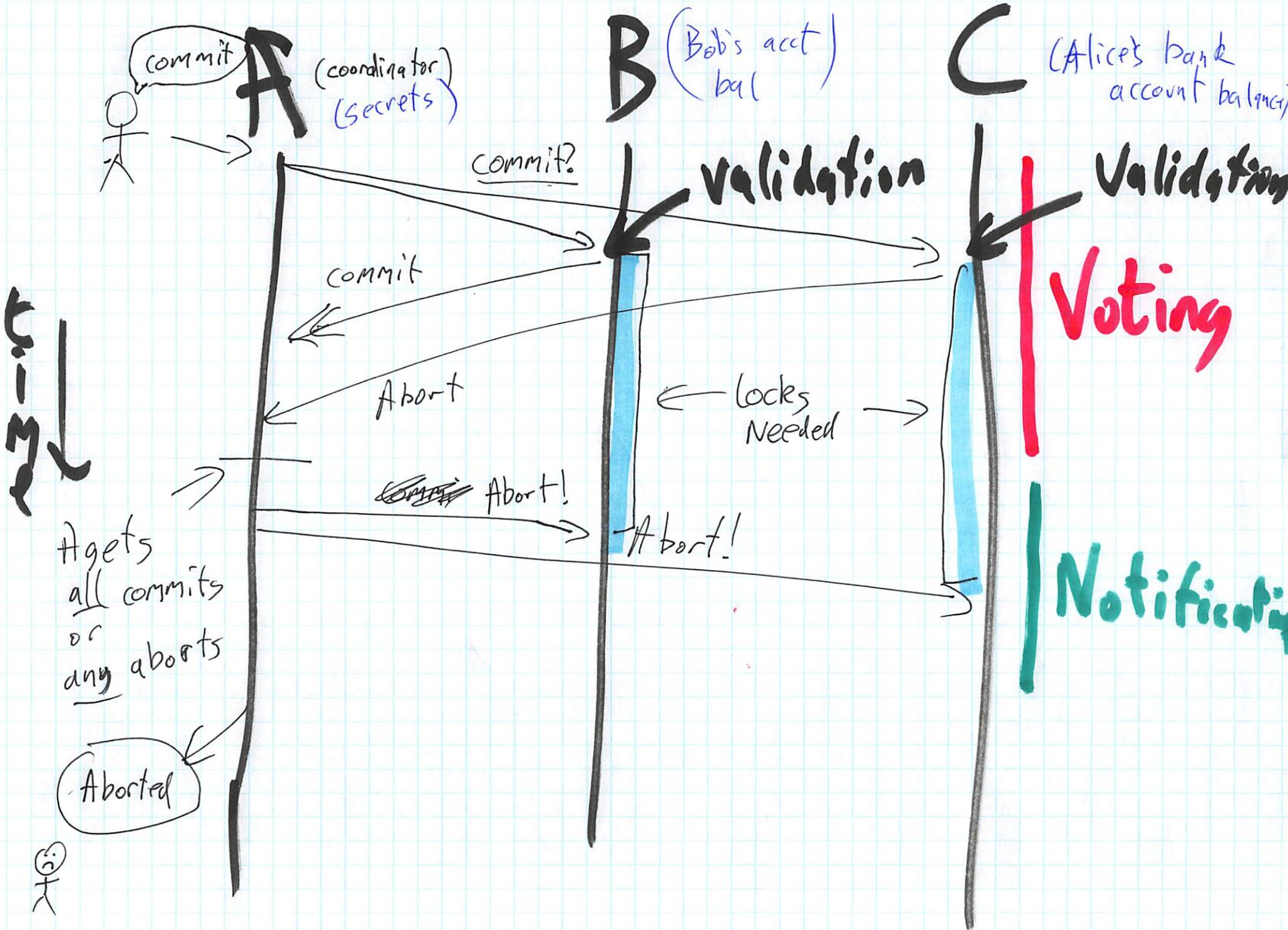
B



C





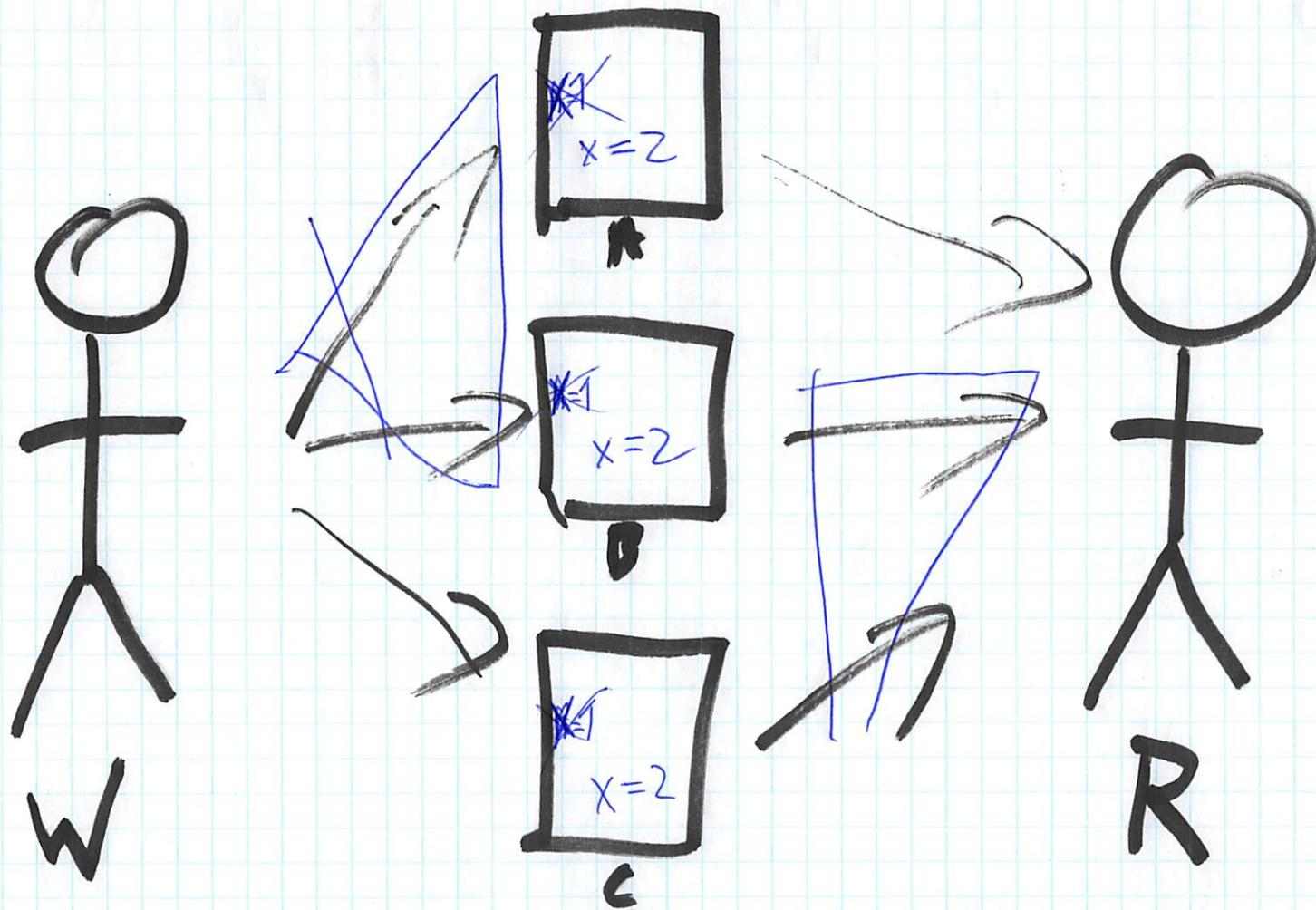


2PC

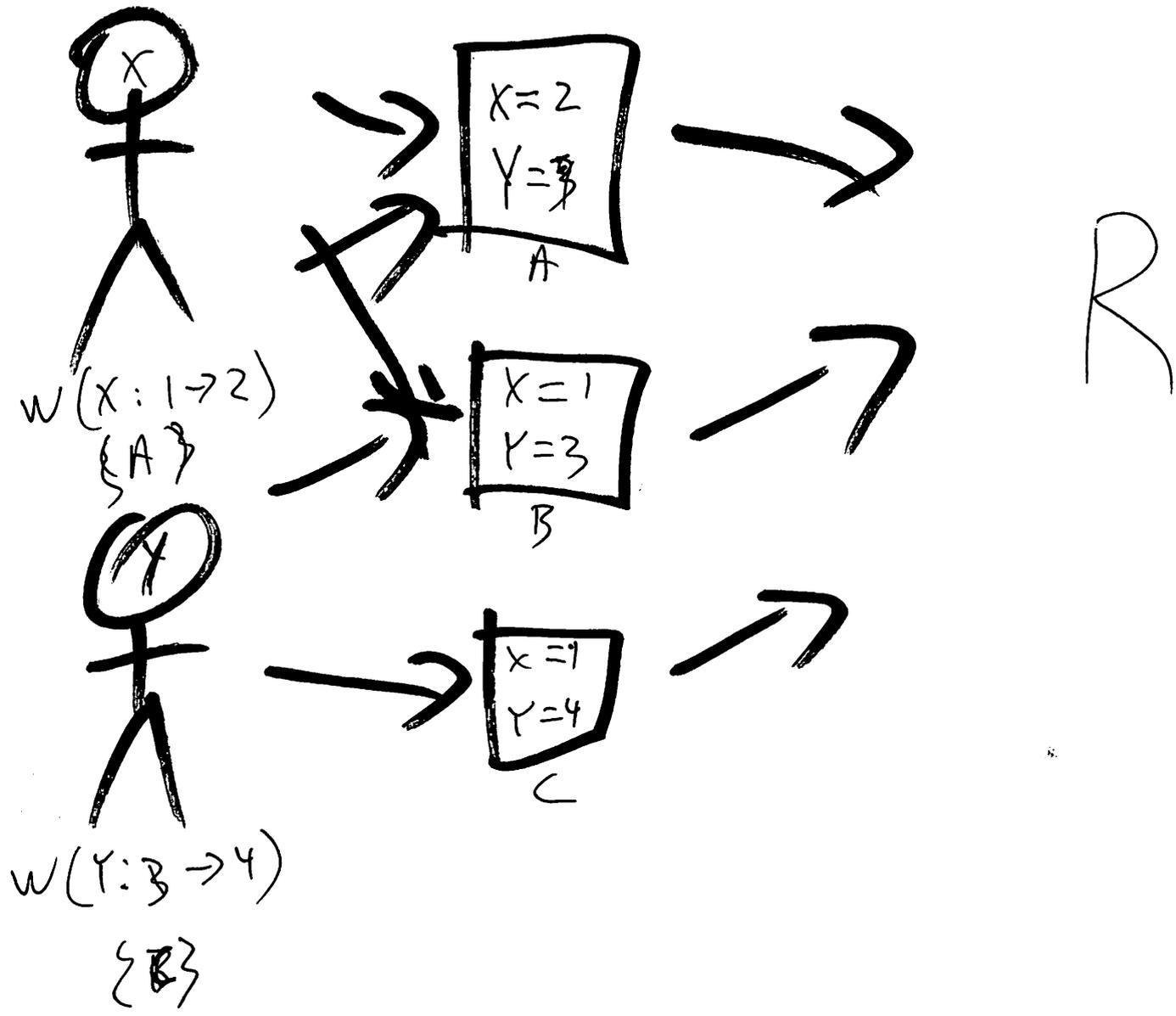
A gets all commits or any aborts

Aborted





\checkmark $\underline{W(x=2)}$
 tell R "ready" \longrightarrow be told "ready"
 $R(x) \rightarrow 2$



w	r
N	1
$\lceil \frac{N}{2} \rceil$	$\lceil \frac{N}{2} \rceil$
1	N

N nodes

w # nodes the writer waits for
 r # nodes the reader waits for

~~$r + w > N$~~ $r + w > N$

$N - w > r$

▼ Parallel Data

▼ Types of Parallelism

▼ Replication (Multiple copies of the same data)

- Better throughput for read-only computations
- Data safety

▼ Partitioning (Different data at different sites)

- More space
- Better throughput for writes
- Sometimes better throughput for read-only computations

▼ Challenges

▼ Replication

- Reading the same value from each site.

▼ Partitioning

- Transactions (Update A and B atomically)

▼ Consensus

▼ Getting everyone to agree on something

- Did a transaction commit?
- In which order were the transactions applied?
- What is the current value of object A?

▼ Techniques

▼ Primary/Secondary (aka Leader/Follower, aka Master/Slave)

▼ Pick one node as the primary

- Deterministic property (lowest IP, etc...)
- Additional consensus protocol for leader selection

▼ Primary is the authoritative version

- All writes go to the primary first.
- Writes are replicated to the secondary(ies) if any exist.
- Secondaries can handle (potentially stale) reads, but not writes

▼ 2-Phase Commit

- Every time something happens, everyone communicates with everyone else.
- All participants signal readiness to participate in consensus
- A temporary, per-consensus task 'leader' signals all other participants to vote
- All participants communicate their vote to the leader.
- ▼ Leader tallies votes based on goal requirements

- k-Data stability requires k replicas to acknowledge
- Commit/Abort requires unanimous acknowledgement
- The leader notifies everyone of the vote result.

▼ Log Consensus

- Sometimes possible. Nodes log messages in an agreed-upon order. Nodes agree to any message they receive in the correct, agreed-upon order.

▼ Failure Modes

▼ Fail-Fast / Fail-Stop

- Software/Hardware failure that causes the node to crash (although it can eventually be restarted)
- The node stops functioning outright — no signs of life at all

▼ Non-Fail-Stop

- Software/Hardware failure that causes the node to behave incorrectly
- The node keeps responding, but does not respond according to the programmer's expectations

▼ Byzantine Faults

- Software/Hardware failure that causes the node to behave as incorrectly as possible.
- The node responds in the most harmful way possible.

▼ Failures

▼ What can fail?

- The node itself
- The network connecting the nodes
- Part of the network connecting the nodes (partition)

▼ Does it matter which?

- If the node crashes, it loses its local state and has to be restarted from scratch
- If the network fails... both nodes continue to be active but are unaware of each other's existence... but may be aware of the existence of other nodes.

▼ Can a node tell which is which?

- No. If Nodes A and B are trying to reach consensus, and B stops responding, A has no clue why.
- So, what happens when the failure condition ends?

▼ Recovery in Primary/Secondary Replicas

▼ Secondary Node Failure

- No Harm. Secondary reboots and rejoins.

▼ Primary Node Failure

- A secondary can rise to take its place... Repeat leader selection process
- Primary reboots as a secondary

▼ Network Failure

- From the point of view of secondaries... identical to primary node failure.

▼ Partitions in Consensus

▼ **Option 1: Assume Node Failure**

- Maximize availability. Promote secondary to primary to ensure that there's always a primary available.
- Creates risk of inconsistency, as there are now two primaries. Two authoritative versions of the data.

▼ **Option 2: Assume Connection Failure**

- Ensure consistency. Wait for network (or primary node) to recover.
- Affects availability. Can't do anything until the primary recovers.

▼ **CAP**

- Consistency, Availability, Partition-Tolerance
- Pick any 2
- More precisely, pick a tradeoff between consistency and availability. How much of each are you willing to sacrifice.

▼ **Reader/Writer Stability**

▼ **In a system with N nodes, you want to read the 'latest' version that everyone agrees on.**

▼ **Failure mode:**

- Receive Ack for write
- Successfully Read an earlier value

▼ **Naive:**

- Write to N nodes, wait for everyone to acknowledge write.
- Read from N nodes, wait for everyone to agree on read.

▼ **Fault-Tolerant**

- Write to N nodes, wait for w nodes to acknowledge write
- Read from N nodes, wait for r nodes to agree on read.
- If $w+r > N$, there must be one overlapping node. Guaranteed to be reading at least latest acked value.
- Can tolerate F failures if $w + r - F > N$